

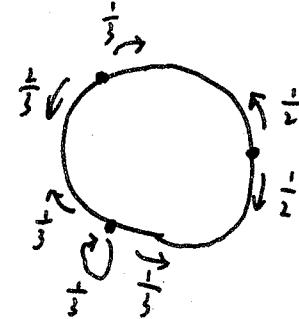
①

1. A general construction of multivariate Markov chains.

Let (S_1, \dots, S_n) be an n -tuple discrete sets, and P_1, \dots, P_n be stochastic matrices defining Markov chains $S_k \rightarrow S_k$.

(e.g. $S = \{e^0, e^{2\pi i/3}, e^{4\pi i/3}\}$.)

$$P = \begin{pmatrix} 0 & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{3} & 0 & \frac{2}{3} \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{pmatrix}$$



Let $\Delta_{k-1}^k, \dots, \Delta_{n-1}^n$ be stochastic links between these sets:

$$\Delta_{k-1}^k : S_k \times S_{k-1} \rightarrow [0, 1], \quad \sum_{y \in S_{k-1}} \Delta_{k-1}^k(x, y) = 1.$$

Assume that they satisfy the commutation relations

$$\Delta_{k-1}^k = \Delta_{k-1}^k P_{k-1} = P_k \Delta_{k-1}^k.$$

or equivalently,

$$\Delta_{k-1}^k(x, y) = \sum_{z \in S_{k-1}} \Delta_{k-1}^k(x, z) P_{k-1}(z, y) = \sum_{w \in S_k} P_k(x, w) \Delta_{k-1}^k(w, y).$$

Then define the multivariate Markov chain on

$$S^{(n)} = \{(x_1, \dots, x_n) \in S_1 \times \dots \times S_n \mid \prod_{k=2}^n \Delta_{k-1}^k(x_k, x_{k-1}) \neq 0\}$$

with the transition matrix $P^{(n)}$ on $S^{(n)}$ as

$$P^{(n)}(x_1, y_1) = P_1(x_1, y_1) \prod_{k=2}^n \frac{P_k(x_k, y_k) \Delta_{k-1}^k(y_k, y_{k-1})}{\Delta_{k-1}^k(x_k, y_{k-1})}$$

We understand the dynamics on $S^{(n)}$ as a sequential update from S_1 to S_n . First, x_1 moves to y_1 with transition

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probability $P_r(x_i, y_i)$; after x_1, \dots, x_{k-1} having moved to y_1, \dots, y_{k-1} , x_k moves to y_k under the condition that $\Lambda_{k-1}^k(y_k, y_{k-1}) \neq 0$, with transition probability const. $P_k(x_k, y_k) \Lambda_{k-1}^k(y_k, y_{k-1})$.

Proposition: Let m_n be a probability measure on S_n . Let $m^{(n)}$ be a probability measure on $S^{(n)}$ defined by

$$m^{(n)}(X_n) = m_n(x_n) \Lambda_{n-1}^n(x_n, x_{n-1}) \cdots \Lambda_1^n(x_2, x_1).$$

Set $\tilde{m}_n = m_n P_n$ (m_n evolves by one step) and let

$$\tilde{m}^{(n)}(X_n) = \tilde{m}_n(x_n) \Lambda_{n-1}^n(x_n, x_{n-1}) \cdots \Lambda_1^n(x_2, x_1)$$

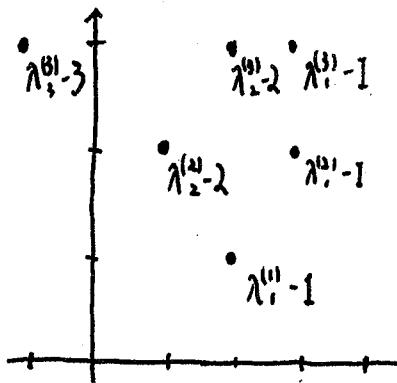
$$\text{Then } m^{(n)} P^{(n)} = \tilde{m}^{(n)}.$$

Rudimentary example:

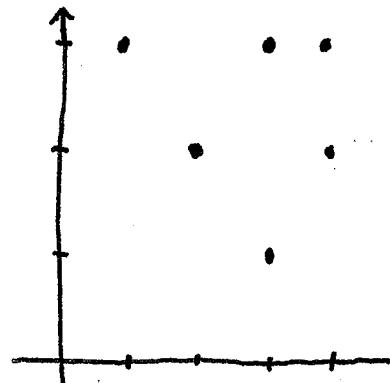
$$\begin{aligned} S_k: Y(k) &= \{ \text{Young tableaux with } k \text{ rows} \} \\ &= \{ (\lambda_1, \dots, \lambda_n) \mid \lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n \geq 0 \}. \end{aligned}$$

$$\Lambda_{k-1}^k((\lambda_1, \dots, \lambda_k), (\mu_1, \dots, \mu_{k-1})) = \begin{cases} 0 & \text{if } \mu \neq \lambda, \text{ i.e., } \lambda_1 \geq \lambda_1 \geq \dots \geq \lambda_{k-1} \geq \mu_{k-1}, \\ & \text{is not satisfied.} \\ \frac{1}{\#\{\nu \in Y(k-1) \mid \nu \leq \lambda\}} & \text{if } \mu \leq \lambda \end{cases}$$

Dynamics:



$P^{(n)}$



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2. Multivariate Markov chains defined by Macdonald polynomials

Let $\lambda, \mu \in Y(k)$ and $\nu \in Y(k-1)$. Define for any a_1, \dots, a_k, b ,

$$P_{\lambda\mu}^{\uparrow}(a_1, \dots, a_k; b) = \frac{1}{\prod(a_1, \dots, a_k; b)} \frac{P_{\mu}(a_1, \dots, a_k)}{P_{\lambda}(a_1, \dots, a_k)} Q_{\mu/\lambda}(b).$$

$$P_{\lambda\nu}^{\downarrow}(a_1, \dots, a_k) = \frac{P_{\nu}(a_1, \dots, a_{k-1})}{P_{\lambda}(a_1, \dots, a_k)} P_{\lambda/\nu}(a_k).$$

Then define the $\infty \times \infty$ matrices

$$P^{\uparrow}(a_1, \dots, a_k; b) = [P_{\lambda\mu}^{\uparrow}(a_1, \dots, a_k; b)]_{\lambda, \mu},$$

$$P^{\downarrow}(a_1, \dots, a_k) = [P_{\lambda\nu}^{\downarrow}(a_1, \dots, a_k)]_{\lambda, \nu}.$$

which are stochastic:

$$\sum_{\mu \in Y(k)} P_{\lambda\mu}^{\uparrow}(a_1, \dots, a_k; b) = 1, \quad \sum_{\nu \in Y(k-1)} P_{\lambda\nu}^{\downarrow}(a_1, \dots, a_k) = 1.$$

Thus $[P_{\lambda\mu}^{\uparrow}]$ defines a transition matrix for $Y(k)$, and $[P_{\lambda\nu}^{\downarrow}]$ defines a stochastic link between $Y(k)$ and $Y(k-1)$.

We can check that they satisfy the commutation relation

$$P^{\uparrow}(a_1, \dots, a_k; b) P^{\downarrow}(a_1, \dots, a_k) = P^{\downarrow}(a_1, \dots, a_k) P^{\uparrow}(a_1, \dots, a_{k-1}; b),$$

or more explicitly

$$\sum_{\mu \in Y(k)} P_{\lambda\mu}^{\uparrow}(a_1, \dots, a_k; b) P_{\lambda\nu}^{\downarrow}(a_1, \dots, a_k) = \sum_{\mu \in Y(k)} \frac{1}{\prod(a_1, \dots, a_k; b)} \frac{P_{\mu}(a_1, \dots, a_{k-1})}{P_{\lambda}(a_1, \dots, a_k)} Q_{\mu/\lambda}(b) P_{\mu/\nu}(a_k)$$

$$\sum_{\mu \in Y(k-1)} P_{\lambda\mu}^{\uparrow}(a_1, \dots, a_k) P_{\mu\nu}^{\downarrow}(a_1, \dots, a_{k-1}; b) = \sum_{\mu \in Y(k-1)} \frac{1}{\prod(a_1, \dots, a_{k-1}; b)} \frac{P_{\nu}(a_1, \dots, a_{k-1})}{P_{\lambda}(a_1, \dots, a_k)} Q_{\mu/\nu}(b) P_{\lambda/\mu}(a_k)$$

$$\left(\text{It is equivalent to check } \frac{\sum_{\mu \in Y(k)} Q_{\mu/\lambda}(b) P_{\mu/\nu}(a_k)}{\sum_{\mu \in Y(k-1)} Q_{\mu/\nu}(b) P_{\lambda/\mu}(a_k)} = \frac{\prod(a_1, \dots, a_{k-1}; b)}{\prod(a_1, \dots, a_k; b)} \right)$$

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Now we define $S_n = Y(n)$, $P_k = P^{\uparrow}(a_1, \dots, a_k; b)$, $P_{k-1}^{\downarrow} = P^{\downarrow}(a_1, \dots, a_k)$.

Then $S^{(n)}$ is the set of Gelfond-Tsetlin patterns

$$S^{(n)} = \{ f(\lambda^{(1)}, \dots, \lambda^{(n)}) \mid \lambda^{(1)} \leq \lambda^{(2)} \leq \dots \leq \lambda^{(n)} \},$$

and the transition matrix $P^{(n)}$ is

$$\begin{aligned} P^{(n)}((\lambda^{(1)}, \dots, \lambda^{(n)}), (\mu^{(1)}, \dots, \mu^{(n)})) &= P_{\lambda^{(1)} \mu^{(1)}}^{\uparrow}(a_1; b) \prod_{k=2}^n \frac{P_{\lambda^{(k)} \mu^{(k)}}^{\uparrow}(a_1, \dots, a_k; b) P_{\mu^{(k-1)}}^{\downarrow}(a_1, \dots, a_k)}{\sum_{\nu \in Y(k)} P_{\lambda^{(k)} \nu}^{\uparrow}(a_1, \dots, a_k; b) P_{\nu, \mu^{(k-1)}}^{\downarrow}(a_1, \dots, a_k)} \\ &= \prod_{k=1}^n P_{a_k, b}(\mu^{(k)} \parallel \mu^{(k-1)}, \lambda^{(k)}). \end{aligned}$$

where

$$P_{a_k, b}(\nu \parallel \lambda, \mu) = \begin{cases} P_{\nu \mu}^{\uparrow}(a_k; b) = \text{const. } P_{\nu}(a_k) Q_{\nu}(b) & \text{if } k=1 \\ \frac{P_{\nu \mu}^{\uparrow}(a_k, \dots, a_k; b) P_{\nu \lambda}^{\downarrow}(a_k, \dots, a_k)}{\sum_{\lambda \in Y(k)} P_{\nu \lambda}^{\uparrow}(a_k, \dots, a_k; b) P_{\lambda}^{\downarrow}(a_k, \dots, a_k)} = \text{const. } P_{\nu/\lambda}(a_k) Q_{\nu/\lambda}(b) & \text{otherwise.} \end{cases}$$

Furthermore, let m_n be the Macdonald measure on $S_n = Y(n)$:

$$m_n(\lambda^{(n)}) = P_{\lambda^{(n)}}(a_1, \dots, a_n) Q_{\lambda^{(n)}}(b_1, \dots, b_n) / \prod (a_i, \dots, a_n; b_i, \dots, b_n).$$

We have that

$$\begin{aligned} \tilde{m}_n(\lambda^{(n)}) &= \sum_{\mu \in Y(n)} m_n(\mu) P_{\mu \lambda^{(n)}}^{\uparrow}(a_1, \dots, a_n; b), \\ &= P_{\lambda^{(n)}}(a_1, \dots, a_n) Q_{\lambda^{(n)}}(b_1, \dots, b_n, b) / \prod (a_i, \dots, a_n; b_i, \dots, b_n, b). \end{aligned}$$

is also a Macdonald measure, with one more b -parameter. We can also check that

$$m^{(n)}(\lambda^{(1)}, \dots, \lambda^{(n)}) = P_{\lambda^{(1)}}(a_1) P_{\lambda^{(2)}/\lambda^{(1)}}(a_2) \cdots P_{\lambda^{(n)}/\lambda^{(n-1)}}(a_n) Q(b_1, \dots, b_n) / \prod (a_i, \dots, a_n; b_i, \dots, b_n)$$

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So by the Proposition,

$$\tilde{m}^{(n)}(\lambda^{(1)}, \dots, \lambda^{(n)}) = m^{(n)} p^{(n)}$$

$$= P_{\lambda^{(1)}}(a_1) P_{\lambda^{(2)}}(a_2) \dots P_{\lambda^{(n)}}(a_n) Q(b_1, \dots, b_m, b) / T(a_1, \dots, a_n; b_1, \dots, b_m, b)$$

is again the Macdonald process.

3. Probabilistic meaning of a simple model.

Consider the simplest case of the Macdonald process: $q = t$, so both P_λ and Q_λ are the Schur polynomial S_λ . Let $a_1 = \dots = a_n = 1$ and $b = p \in (0, 1)$. Note that

$$S_{\lambda/a}(x) = \begin{cases} 0 & \text{if } \mu \neq \lambda, \\ x^{|\lambda| - |\mu|} & \text{if } \mu \leq \lambda. \end{cases}$$

The movement of the Gelfond-Tsetlin pattern $(\lambda^{(1)}, \dots, \lambda^{(n)})$ to $(\mu^{(1)}, \dots, \mu^{(n)})$ can be described as follows, equivalent to $p^{(n)}$:
 First. $\lambda_i^{(1)}$ jumps right to $\mu_i^{(1)} \geq \lambda_i^{(1)}$ with probability const. $p^{\mu_i^{(1)} - \lambda_i^{(1)}}$, where const. $= 1 - p$.

Second. $\lambda_i^{(1)}$ jumps right to $\mu_i^{(1)} \geq \max(\lambda_i^{(2)}, \mu_i^{(1)})$ with probability const. $p^{\mu_i^{(1)} - \lambda_i^{(1)}}$, and $\lambda_i^{(2)}$ jumps right to $\mu_i^{(2)}$ that satisfies $\lambda_i^{(2)} \leq \mu_i^{(2)} \leq \mu_i^{(1)}$, with probability const. $p^{\mu_i^{(2)} - \lambda_i^{(2)}}$. Here the two constants depend on $\lambda^{(1)}, \mu^{(1)}$ but not $\mu^{(2)}$.

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Third. $\lambda_1^{(3)}$ jumps right to $M_1^{(3)} \geq \max(\lambda_1^{(3)}, M_1^{(2)})$.

$\lambda_2^{(3)}$ jumps right to $M_2^{(3)}$ such that $\max(\lambda_2^{(3)}, M_2^{(2)}) \leq M_2^{(3)} \leq M_1^{(2)}$

$\lambda_3^{(3)}$ jumps right to $M_3^{(3)}$ such that $\lambda_3^{(3)} \leq M_3^{(3)} \leq M_2^{(2)}$.

with probabilities const. $p^{M_i^{(3)} - \lambda_i^{(3)}}$, $i=1,2,3$, where the constants depend on $\lambda^{(3)}$ and $M^{(2)}$ but not $M^{(3)}$

It is clear that the movement of $\lambda_1^{(1)}, \lambda_2^{(2)}, \dots, \lambda_n^{(n)}$ is independent to other entries in the Gelfond-Tsetlin pattern. Suppose $x_k = \lambda_k^{(k)} - k$ are positions of particles on \mathbb{Z} . $x_1 > x_2 > \dots > x_n$. Then their movement, in one step, is:

First. x_1 jumps to the right k_1 units in probability $(1-p)p^{k_1}$.
($k_1 = 0, 1, 2, \dots$).

Second. x_2 jumps to the right k_2 units in probability $\frac{1-p}{1-px_1+k_1-x_2} p^{k_2}$.
($k_2 = 0, 1, \dots, x_1 + k_1 - x_2 - 1$).

Third. x_3 jumps to the right k_3 units in probability $\frac{1-p}{1-px_2+k_2-x_3} p^{k_3}$.
($k_3 = 0, 1, \dots, x_2 + k_2 - x_3 - 1$)



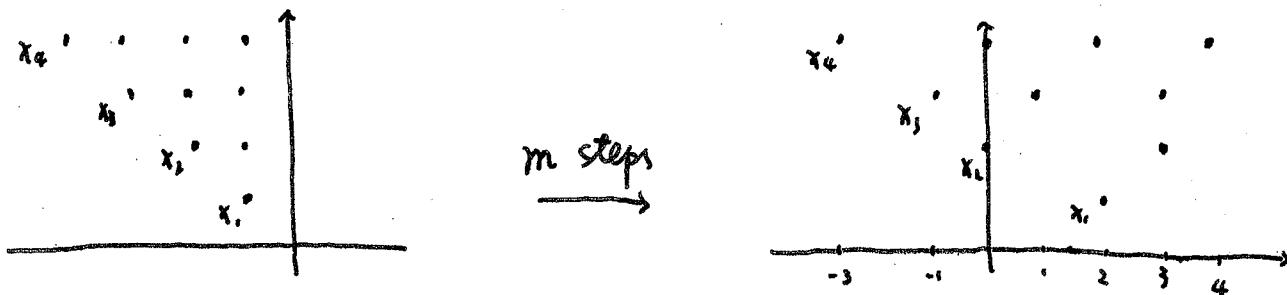
Question: if $x_k = -k$ ($k=1, \dots, n$) initially, what's the

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distribution of x_n after m steps?

Answer: the same as the distribution of $\pi_m^{(n)} - n$, where $\lambda^{(n)} = (\lambda_1^{(n)}, \dots, \lambda_m^{(n)})$ is in the Macdonald measure

$$MM\left(\underbrace{1, \dots, 1}_n : \underbrace{p, \dots, p}_m\right) \quad (\text{actually Schur measure})$$



Initially, $(\lambda_1^{(n)}, \dots, \lambda_m^{(n)})$ are frozen to $\lambda^{(n)} = (\underbrace{0, \dots, 0}_k)$, since they are in the distribution of the Macdonald process with $a_1 = \dots = a_n = 1$, $b_1 = \dots = b_m = 0$.

After m steps, $(\lambda_1^{(n)}, \dots, \lambda_m^{(n)})$ are in the distribution of the Macdonald process with $a_1 = \dots = a_n = 1$, $b_1 = \dots = b_m = p$ (after each step, one p is added). (actually Schur process)

(The figures above show $\pi_j^{(n)} - j$ to make dots not overlapped).

4. Continuous limits.

It is straight forward to get the continuous limit of the particle model considered above, as $p \rightarrow 0_+$.

Each particle x_i has an exponential clock that is working as long as its right neighbour site is not occupied by x_{i+1} , otherwise

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the exponential clock is paused until x_{k-1} moves away. When the clock clicks, x_k moves to the right by one unit.

This is the celebrated totally asymmetric simple exclusion process (TASEP).

The distribution of x_n after time t is given by $\pi_t^{(n)} - n$ where $\pi^{(n)}$ is in the Macdonald / Schur measure $MM(\underbrace{1, \dots, 1}_n; p)$, and p is the limiting Plancheral specialization depending on t .

A variation of TASEP: Each particle x_k has an exponential clock that is slower if x_{k-1} is near to it: The parameter is $(1 - q^{x_{k-1} - x_k - 1})$. (so if x_{k-1} is at the right neighbour site to x_k , the exponential clock stops.). This is called the q -TASEP.

The distribution of x_n after time t , suppose the initial condition is $x_k = -k$, is given again by $\pi_t^{(n)} - n$, where $\pi^{(n)}$ is in the Macdonald measure $MM(\underbrace{1, \dots, 1}_n; p)$, but now the t and q parameters are $t \rightarrow 0$, $q = f$. This is the q -whittaker measure.